Algorithmic Need for Subcopulas

Thach N. Nguyen  
*Banking University of Ho Chi Minh City*, ajeb@buh.edu.vn

Olga Kosheleva  
*The University of Texas at El Paso*, olgak@utep.edu

Vladik Kreinovich  
*The University of Texas at El Paso*, vladik@utep.edu

Nguyen Hoang Phuong  
*Thang Long University*, nhphuong2008@gmail.com

Follow this and additional works at: [https://scholarworks.utep.edu/cs_techrep](https://scholarworks.utep.edu/cs_techrep)

Part of the *Computer Sciences Commons*

Comments:


[https://doi.org/10.1007/978-3-030-04263-9_13](https://doi.org/10.1007/978-3-030-04263-9_13)

**Recommended Citation**

[https://scholarworks.utep.edu/cs_techrep/1233](https://scholarworks.utep.edu/cs_techrep/1233)

This Article is brought to you for free and open access by the Computer Science at ScholarWorks@UTEP. It has been accepted for inclusion in Departmental Technical Reports (CS) by an authorized administrator of ScholarWorks@UTEP. For more information, please contact lweber@utep.edu.
Algorithmic Need for Subcopulas

Thach Ngoc Nguyen, Olga Kosheleva, Vladik Kreinovich, and Hoang Phuong Nguyen

Abstract One of the efficient ways to describe the dependence between random variables is by describing the corresponding copula. For continuous distributions, the copula is uniquely determined by the corresponding distribution. However, when the distributions are not continuous, the copula is no longer unique, what is unique is a subcopula, a function $C(u,v)$ that has values only for some pairs $(u,v)$. From the purely mathematical viewpoint, it may seem like subcopulas are not needed, since every subcopula can be extended to a copula. In this paper, we prove, however, that from the algorithmic viewpoint, it is, in general, not possible to always generate a copula. Thus, from the algorithmic viewpoint, subcopulas are needed.

1 Formulation of the Problem

Copulas: a brief reminder. There are many ways to describe a probability distribution of a random variable:

- we can use its probability density function (pdf),
- we can use its moments,
- its cumulative distribution function (cdf), etc.

Most of these types of descriptions are not always applicable:
for a discrete distribution, pdf is not defined,
- for a distribution with heavy tails, moments are sometimes infinite, etc.

Out of the known representations, the representation as a cdf is the most universal, it does not seem to have limitations. In view of this, to take into account that in econometrics, one can encounter discrete distributions (for which no pdf is known), heavy-tailed distributions (for which moments are infinite), etc., it is reasonable to use a cdf

$$F_X(x) = \text{Prob}(X \leq x)$$

to describe a random variable $X$.

Similarly, to describe a joint distribution of two random variables $(X, Y)$, it is reasonable to use a joint cdf

$$F_{XY}(x, y) = \text{Prob}(X \leq x \land Y \leq y).$$

When random variables $X$ and $Y$ are independent, we have $F_{XY}(x, y) = F_X(x) \cdot F_Y(y)$.

In general, the dependence may be more complicated. It is reasonable to describe this dependence by a function $C(u, v)$ for which

$$F_{XY}(x, y) = C(F_X(x), F_Y(y)).$$

(1)

A function with this property is known as a copula; see, e.g., [3, 6, 7, 8]. Copulas have been successful used in many application areas, in particular, in econometrics.

**Existence and uniqueness of copulas.** It has been proven that such a copula always exists, and that the copula function $C(u, v)$ is itself a 2-D cdf on the square $[0, 1] \times [0, 1]$.

In situations when the distributions of $X$ and $Y$ are continuous – e.g., when there exists pdf’s – the copula is uniquely determined. Indeed, in this case, the value $F_X(x)$ continuously depends on $x$ and thus, attains all possible values between 0 and 1. So, to find $C(u, v)$, it is sufficient to find the values $x$ and $y$ for which $F_X(x) = u$ and $F_Y(y) = v$, then $F_{XY}(x, y)$ will give is the desired value of $C(u, v)$.

However, if the distribution of one of the variables – e.g., $X$ – is discrete (for example, there are some values which have positive probabilities), then the value $F_X(x)$ jumps, and for thus, for some intermediate values $u$, we do not have values $x$ for which $F_X(x) = u$. In such situations, the copula is not uniquely determined, since we can have different values $C(u, v)$ for this jumped-over $u$.

**Subcopulas: reminder.** While the copula is not always unique, there is a variant of this notion which is always unique; this variant is known as a subcopula. In precise terms, a subcopula is also defined by the formula (1), the only difference is that:

- while a copula has to be defined for all possible values $u \in [0, 1]$ and $v \in [0, 1]$,
- a subcopula $C(u, v)$ is only defined for the values $u$ and $v$ which have the form $u = F_X(x)$ and $v = F_Y(y)$ for some $x$ and $y$. 

Subcopulas have also been successfully used in econometrics; see, e.g., [9, 11, 13, 14, 17].

**Main question: do we need subcopulas?** From the purely mathematical viewpoint, it may seem that do not need subcopulas, since every subcopula can be, in principle, extended to a copula.

However, the fact that many researchers use subcopulas seem to indicate that, from the algorithmic viewpoint, subcopulas may not be easy to extend to copulas. An indirect argument in support of this not-easiness is that known extension proofs use non-constructive arguments such as Zorn’s Lemma (which is equivalent to a non-constructive Axiom of Choice); see, e.g., [2].

**What we do in this paper.** In this paper, we prove that indeed, in situations of non-uniqueness, it is not algorithmically possible to always construct a copula. In other words, we prove that, from the algorithmic viewpoint, subcopulas are indeed needed.

## 2 What Is Computable: A Brief Reminder

**What is computable: main definitions.** In order to analyze when a copula is computable and when it is not, let us recall the main definitions of computability; for details, see, e.g., [1, 4, 15] (for random variables, see also [5]).

A real number $x$ is *computable* if we can compute it with any given accuracy. In other words, a number is computable if there exists an algorithm that, given an integer $n$ (describing the accuracy), returns a rational number $r_n$ for which

$$|x - r_n| \leq 2^{-n}.$$  

Intuitively, a function $f(x)$ is computable if there is an algorithm that, given $x$, returns the value $f(x)$. In precise terms, this means that for any desired accuracy $n$, we can compute a rational number $r_n$ for which $|f(x) - r_n| \leq 2^{-n}$; in this computation, the program can pick some integer $m$ and ask for an $2^{-m}$-approximation to the input.

Similarly, a function $f(x, y)$ of two variables is called computable if, given $x$ and $y$, it can compute the value $f(x, y)$ with any given accuracy. Again, in the process of computations, this program can pick some $m$ and ask for a $2^{-m}$-approximation to $x$ and to $y$.

**Comment.** These definitions describe the usual understanding of computability; so, not surprisingly, all usual computable functions – e.g., all elementary functions, all continuous functions – are computable in this sense as well.

**What is not computable.** What is not computable in this sense are discontinuous functions such as $\text{sign}(x)$ which is equal:

- to $-1$ when $x < 0$,  

to 0 when \( x = 0 \), and
\( x > 0 \).
Indeed, if this function was computable, then we would be able to check whether a computable real number is equal to 0 or not, and such checking is not algorithmically possible; see, e.g., [4] and references therein.
Indeed, the possibility of such checking contradicts to the known result that it is not possible,
\( \bullet \) given a program,
\( \bullet \) to check whether this program halts or not.
Indeed, based on each program, we can form a sequence \( r_n \) each element of which is:
\( \bullet \) equal to \( 2^{-n} \) if the program did not yet halt by time \( n \) and
\( \bullet \) equal to \( 2^{-t} \) if it halted at time \( t \leq n \).
Then:
\( \bullet \) If the program does not halt, this sequence describes the computable real number 
\[ x = 0. \]
\( \bullet \) If the program halts at time \( t \), this sequence describes the computable real number 
\[ x = 2^{-t} > 0. \]
Thus, if we could check whether a real number is equal to 0 or not, we would be able to check whether a program halts or not – and we know that this is not algorithmically possible.

**What does it mean for the cdf to be computable.** In real life, when we say that we have a random variable, it means that we have a potentially infinite sequence of observations which follow the corresponding distribution. Based on these observations, for each computable real number \( x \), we would like to compute the value \( F(x) \).

The value \( F(x) \) is the probability that the value of a random variable \( X \) is \( \leq x \). A natural practical way to estimate a probability based on a finite sample is to estimate the frequency of the corresponding event. Thus, to estimate \( F(x) \), a natural idea is to take \( n \) observations \( X_1, \ldots, X_n \), find out how many of them are \( \leq x \), and then compute the desired frequency by dividing the result of the counting by \( n \).

Even in the ideal case, when all the values \( X_i \) are measured exactly, the frequency is, in general, different from the probability. It is known (see, e.g., [12]) that for large \( n \), the difference between the frequency \( f \) and the probability \( p \) is approximately normally distributed, with 0 means and standard deviation
\[
\sigma = \sqrt{\frac{p \cdot (1-p)}{n}} \leq \frac{0.5}{\sqrt{n}}.
\]
From the practical viewpoint, any deviation larger than 6 sigma has a probability of less than $10^{-8}$ and is, thus, usually considered practically impossible. (If you do not view 6 sigma as impossible, take 20 sigma; one can always come up with a probability so small that it is practically impossible.) Thus, if for a given $\varepsilon > 0$, we select $n$ so large that $6\sigma \leq 6 \cdot \frac{0.5}{\sqrt{n}} \leq \varepsilon$ Then, the resulting frequency $f$ is guarantee to be $\varepsilon$-close to the desired probability $F(x)$: $|f - F(x)| \leq \varepsilon$, i.e., equivalently, $F(x) - \varepsilon \leq f \leq F(x) + \varepsilon$.

In practice, we also need to take into account that the values $X_i$ can only be measured with a certain accuracy $\delta$; see, e.g., [10]. Thus, what we compare with the given number $x$ are not the actual values $X_i$ but the results $\bar{X}_i$ of their measurement which are $\delta$-close to $X_i$:

- If $\bar{X}_i \leq x$, we cannot conclude that $X_i \leq x$, we can only conclude that $X_i \leq x + \delta$.
- Similarly, if $\bar{X}_i > x$, we cannot conclude that $X_i > x$, we can only conclude that $X_i > x - \delta$.

Thus, the only think that we can guarantee for the observed frequency $f$ is that

$$ F(x - \delta) - \varepsilon \leq f \leq F(x + \delta) + \varepsilon. \quad (2) $$

This is how a computable cdf is defined: that, given every a computable number $x$ and rational numbers $\varepsilon > 0$ and $\delta > 0$, we can efficiently find a rational number $f$ that satisfies the inequality (2).

A similar inequality

$$ F(x - \delta, y - \delta) - \varepsilon \leq f \leq F(x + \delta, y + \delta) + \varepsilon \quad (3) $$
defines a computable 2-D cdf.

Comment. Note that a cdf can be discontinuous – e.g., if we have a random variable that is equal to 0 with probability 1, then:

- $F(x) = 0$ for $x < 0$ and
- $F(x) = 1$ for $x \geq 0$.

We already know such a function cannot be computable, so a computable cdf is not necessarily a computable function.

However, as we will see, when the computable cdf is continuous, it is a computable function.

**Proposition 1.** When the distributions are continuous, a computable cdf is a computable function.

**Proof.** Indeed, the inequalities (2) can be rewritten as follows:

$$ f_{\delta, \varepsilon}(x - \delta) - \varepsilon \leq F(x) \leq f_{\delta, \varepsilon}(x + \delta), \quad (3) $$
Thach Ngoc Nguyen, Olga Kosheleva, Vladik Kreinovich, and Hoang Phuong Nguyen

where \( f_{\delta,\varepsilon}(x) \) means a frequency estimated by comparing the measured values \( \tilde{X}_i \) (measured with accuracy \( \delta \)) with the value \( x \), based on a sample large enough to guarantee the accuracy \( \varepsilon \).

Also, due to (2), we have

\[
F(x - 2\delta) - \varepsilon \leq f_{\delta,\varepsilon}(x - \delta) \quad \text{and} \quad f_{\delta,\varepsilon}(x + \delta) \leq F(x + 2\delta) + \varepsilon,
\]

thus

\[
F(x - 2\delta) - 2\varepsilon \leq f_{\delta,\varepsilon}(x - \delta) - \varepsilon \leq F(x) \leq f_{\delta,\varepsilon}(x + \delta) + \varepsilon \leq F(x + 2\delta) + 2\varepsilon. \tag{4}
\]

When the cdf \( F(x) \) is a continuous function, then, for each \( x \), the difference

\[
F(x + 2\delta) - F(x - 2\delta)
\]

tends to 0 as \( \delta \) decreases. Thus, the difference between the values \( F(x + 2\delta) + 2\varepsilon \) and \( F(x - 2\delta) - 2\varepsilon \) also tends to 0 as \( \delta \to 0 \) and \( \varepsilon \to 0 \). Thus, if we take \( \delta = \varepsilon = 2^{-k} \) for \( k = 1, 2, \ldots \), we will eventually encounter an integer \( k \) for which this difference is smaller than a given number \( 2^{-n} \). In this case, due to (4), the difference between the inner bounds \( f_{\delta,\varepsilon}(x + \delta) + \varepsilon \) and \( f_{\delta,\varepsilon}(x - \delta) - \varepsilon \) is also \( \leq 2^{-n} \).

Thus, to compute \( F(x) \) with accuracy \( 2^{-n} \), it is sufficient to compute, for \( k = 1, 2, \ldots \),

- values \( \varepsilon = \delta = 2^{-k} \) and then
- values \( f_{\delta,\varepsilon}(x + \delta) + \varepsilon \) and \( f_{\delta,\varepsilon}(x - \delta) - \varepsilon \).

We continue these computations for larger and larger \( k \) until the difference between \( f_{\delta,\varepsilon}(x + \delta) + \varepsilon \) and \( f_{\delta,\varepsilon}(x - \delta) - \varepsilon \) becomes smaller than or equal to \( 2^{-n} \).

Once this condition is satisfied, we return \( f_{\delta,\varepsilon}(x + \delta) + \varepsilon \) as the desired \( 2^{-n} \)-approximation to \( F(x) \).

The proposition is proven.

**Comment.** In the 2-D case, we can use a similar proof.

### 3 Main Results and Their Proofs

**Proposition 2.** There exists an algorithm that, given a continuous computable cdf \( F_{XY}(x,y) \), generates the corresponding copula – i.e., generates a computable cdf \( C(u,v) \) that satisfies the formula (1).

**Proposition 3.** No general algorithm is possible that, given a computable cdf \( F_{XY}(x,y) \), would generate the corresponding copula – i.e., that would generates a computable cdf \( C(u,v) \) that satisfies the formula (1).
Comment. This result proves that from the algorithmic viewpoint, it is, in general, not possible to always generate a copula. Thus, from the algorithmic viewpoint, subcopulas are indeed needed.

Proof of Proposition 2. This proof is reasonably straightforward, it follows the above idea of finding the copula for a continuous cdf.

Indeed:

- suppose that we are given two computable numbers $u,v \in [0,1]$, and
- we want to find the desired approximation to the value $C(u,v)$.

To do that, we first find $x$ for which $F_X(x)$ is $\delta$-close to $u$.

This value can be found as follows. First, we pick any $x_0$ and compute $F_X(x_0)$ with accuracy $\delta$; we can do it, since, according to Proposition 1, for continuous distributions, the cdf is a computable function. If we get a value which is $\delta$-close to $u$, we are done.

If the approximate value $F_X(x_0)$ is larger than $u$, we take $x_0 - 1$, $x_0 - 2$, etc., until we find a new value $x_+$ for which $F_X(x_+) < u$.

Similarly, if the approximate value $F_X(x_0)$ is smaller than $u$, we take $x_0 + 1$, $x_0 + 2$, etc., until we find a new value $x_-$ for which $F_X(x_-) > u$.

In both cases, we have an interval $[x_-,x_+]$ for which $F(x_-) < u < F(x_+)$. Now, we can use bisection to find the desired $x$: namely, we take a midpoint $x_m$ of the interval. Then:

- If $|F_X(m) - u| \leq \delta$, we are done.
- If this ideal inequality is not satisfied, then we have:
  - either $F_X(x_m) < u$
  - or $F_X(x_m) > u$.

- In the first case, we know that the desired value $x$ is in the half-size interval $[x_m,x_+]$.
- In the second case, we know that the desired value $x$ is in the half-size interval $[x_-,x_m]$.

- In both cases, we get a new half-size interval.

To the new interval, we apply the same procedure until we get the desired $x$.

Similarly, we can compute $y$ for which $F_Y(y) \approx v$. Now, we can take the approximation to $F_{XY}(x,y)$ as the desired approximation to $C(u,v)$.

The proposition is proven.

Proof of Proposition 3. For each real number $a$ for which $|a| \leq 0.5$, we can form the following probability distribution $F_a(x,y)$ on the square $[0,1] \times [0,1]$: it is uniformly distributed on a straight line segment $y = 0.5 + \text{sign}(a) \cdot (x - 0.5)$ corresponding to $x \in [0.5 - |a|, x + |a|]$. Thus:

- when $a > 0$, we take $y = x$; and
when $a < 0$, we take $y = 1 - x$.

One can easily check that $F_x(x, y)$ is indeed a computable cdf – although it is not always a computable function, since, e.g., for $a = 0$ the whole probability distribution is concentrated at the point $(0.5, 0.5)$.

For each $a$, the marginal distribution $F_x(x)$ is uniformly distributed on the interval $[0.5 - |a|, 0.5 + |a|]$ of length $2|a|$. Thus, for the values $x$ from this interval, we have

$$F_x(x) = \frac{x - (0.5 - |a|)}{2|a|}.$$  

So for any $u \in [0, 1]$, to get $F_x(x) = u$, we must take

$$x = 0.5 - |a| + 2u \cdot |a| = 0.5 - (1 - 2u) \cdot |a|.$$  

Similarly, to get the value $y$ for which $F_Y(y) = v$, we should take

$$y = 0.5 - (1 - 2v) \cdot |a|.$$  

For $u, v \leq 0.5$, we get $x \leq 0.5$ and $y \leq 0.5$.

In particular, for $u = v = 0.25$, we should take $x = y = 0.5 - 0.5|a|$, and for $u = v = 0.5$, we should take $x = y = 0.5$.

Since the distribution is symmetric, when $u = v$, we have the same values $x = y$ for which $F_x(x) = u$ and $F_Y(y) = u$.

- When $a > 0$, we have $X = Y$. Thus for every $u = v$, we have

$$C(u, u) = F_{XY}(x, x) = \text{Prob}(X \leq x \& Y \leq x) = \text{Prob}(X \leq x) = u,$$

i.e., $C(u, u) = u$. In particular, we have

$$C(0.25, 0.25) = 0.25 \quad \text{and} \quad C(0.5, 0.5) = 0.5.$$  

- When $a < 0$, then $Y = 1 - X$. Thus, when $X \leq 0.5$, we have $Y \geq 0.5$, so when $u, v \leq 0.5$, we cannot have both $X \leq u$ and $Y \leq v$, and thus, we get

$$C(u, u) = F_{XY}(x, x) = \text{Prob}(X \leq x \& Y \leq x) = 0.$$  

In particular, we have $C(0.25, 0.25) = C(0.5, 0.5) = 0$.

If it was possible, given a computable real number $a$, to compute a computable cdf $C(u, v)$, then, by definition of a computable cdf, we would be able to compute:

- given $a$,
- the value $f_{\delta, \epsilon}(x)$ corresponding to $x = 0.375$, $\delta = 0.125$ and $\epsilon = 0.1$, i.e., the value $f \overset{\text{def}}{=} f_{0.125, 0.1}(0.375)$ for which

$$C(x - \delta, x - \delta) - \epsilon \leq f \leq C(x + \delta, x + \delta) + \epsilon,$$
i.e., for which
\[ C(0.25, 0.25) - 0.1 \leq f \leq C(0.5, 0.5) + 0.1. \]

Here:
- when \( a < 0 \), we have \( C(0.5, 0.5) = 0 \), hence \( f \leq 0.1 \) and therefore \( f < 0.125 \);
- when \( a > 0 \), then \( C(0.25, 0.25) = 0.25 \), hence \( f \geq 0.15 \) and therefore \( f > 0.125 \).

So, by comparing the resulting value \( f \) with 0.125, we will able to check whether \( a > 0 \) or \( a < 0 \) – and this is known to be algorithmically impossible; see, e.g., [1, 4, 15]. This contradiction shows that it is indeed not possible to have an algorithm that always computes the copula.

The proposition is proven.

Acknowledgments

This work was supported in part by the US National Science Foundation via grant HRD-1242122 (Cyber-ShARE Center of Excellence).

The authors are thankful to Professor Hung T. Nguyen for valuable discussions.

References